



Model NAVpilot-1000









The NAVpilot-1000 is a HCS (Heading Control System) type-approved Autopilot that can be connected to an analog steering system or solenoid steering system, which are often used for relatively large vessels. The NAVpilot-1000 has both IMO and Non-IMO modes depending on steering types or operation requirements and covers various types of vessels.

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Steering Straight with AUTO Mode

The NAVpilot-1000 takes the helm with an advanced steering algorithm that is designed for larger vessels. Specially designed features, like TURN Mode, ensure that you make smooth turns with confidence.

Work Profiles

When vessels are operated on a daily basis, sea conditions are different depending on weather or locations. In addition, preference on how-to-steer is also different depending on operators. The NAVpilot-1000 can save a total of six (6) patterns of Work Profiles. Parameters set in Auto Tuning or manual adjustment can be assigned to each profile. Simply select one of the suitable profiles for the day, location or operator.

Auto Tuning

Before navigating with the NAVpilot-1000, Auto Tuning helps to adjust control parameters. While Auto Tuning, the vessel will run in zig-zag towards the preset heading and automatically adjust rudder gain, counter rudder, and rate of turn to match with vessel characteristics.





- ► HCS (Heading Control System) type-approved Autopilot
- Both IMO and Non-IMO Configurations Available
- The NAVpilot-1000 covers larger boats from commercial vessels to luxury yachts.

HCS Type-Approved

NAVpilot-1000 received the Type Approval certification for the Heading Control System (HCS) and Heading control system for high speed craft. The Type Approval certifies that the product meets specific safety, quality, and reliability standards required for the international marine industry.





Easy to Read and Robust Controls

The NAVpilot-1000 comes with a 5.7" color control unit. Large, high-contrast characters are easy to read on the color LCD. The robust rotary knob and buttons are comfortable to rotate and press even in rough sea conditions.

6

Easily Follow Routes with NAV Mode North NAV Mode

The NAVpilot-1000 helps steer vessels on a monitored or activated route with NAV mode.

Interconnect with MFD

The NAVpilot-1000 can be connected to FURUNO's NavNet TZtouch series MFDs^{*1}via NMEA2000. AUTO and NAV modes can be activated from the MFD screen, as well as adjusting the set course while navigating.

1 TZT10X/13X/16X/22X/24X: All software versions TZT9F/12F/16F/19F: Software version 3.56 or later TZT2BB: Software varion 9.56 or later



*Photo: NavNet TZtouch3 TZT19F

SPECIFICATI		*The NAVpilot-1000 is de	esigned for use on100 m or smaller vessels.
CONTROL UNIT		INTERFACE	
Display	5.7-inch color LCD. 640 x 480 dots (VGA)	Number of ports	
Brilliance	720 cd/m ²	Serial	4 ports, I/O, IEC61162-1 Ed.3 to 5, NMEA0183
Max. number of units	6 units (requires external 9-16 V power source and		Ver1.5/2.0, 4800/38400 bps
in a network	isolator for connection of 4 or more units)	LAN	1 port, Ethernet 100Base-TX, IEEE802.3 data
Language	English		1 port for control unit
		Liniversal output	6 ports (dn/ contact) alarm/status: 100 mA max
PROCESSOR UNIT		Liniversal input	4 ports (dny contact)
Steering mode	STBY, AUTO, Advanced AUTO, NAV*1(Standard/Precision),	Power failure	1 port $12-24$ V· 100 mA max
	FU-RC*2, NFU-RC*1 *2, FU-KEY*2, NFU-KEY*2,	Changeover switch	1 port (input)
	DISENGAGED (FU/NFU: Follow-Up/Non-Follow-UP,	USB	1 port, USB 2.0, for maintenance
	RC/KEY: remote/keyboard control)		
	*1: Non-IMO mode only, *2: Available only when the RRU is installed.	POWER SUPPLY	
Rudder gain	Auto / Manual	Processor unit	12-24 VDC (10.8-31.2 V): 4.0-2.0 A
Counter rudder	Auto / Manual		(control unit: 3 units)
Trim gain	Auto / Manual		
Rate of turn	0.1-10 dea/s	ENVIRONMENTAL CONDITIONS	
Rudder angle settings	±45 deg	Ambient temperature	-15 °C to +55 °C (storage: -30 °C to -70 °C)
Alert	Heading monitor. Watch. Off heading	Relative humidity	93% or less at +40 °C
Rudder control (analog)		waterprooning	Processor Init: IP22
Voltage	0 to 5 V (min.)10 to +10 V (max.) (5 mA max.)		
Current	4 to 20 mA (load resistance 500 ohm max.)	EQUIPMENT LIST	
Solenoid control for rudder on/off		Standard Control Unit	545 40004
Isolation	Galvanic/non-galvanic isolation	Processor Linit	FAP-10001
Connection	Common negative	Installation Materials	FAF-10002
Load range	3 A max.	Spare parts	
Clutch / Bypass drive for rudder		Optional Supply	
Isolation	Galvanic/non-galvanic isolation	Control Unit	FAP-10001
Connection	Common negative	Rudder Reference Unit	FAP-6112
Load range	3 A max.	NMEA2000 Junction Box	FI-5002
		Cable Assembly	FRU-NMEA-PFF 1/2/6 m
			FRU-NMFA-PMMFF 1/2/6 m



Control Unit FAP-10001 Control Unit FAP-10001 NMEA2000 IEC61162-1/2 Alert Management System 9-16 VDC IEC61162-450 Hub Processor Unit FAP-10002 Power Fai Changeo 12-24 VDC Steering System Rudder Reference Unit*2 An emergency stop method is required for safety at emergency. Refer to Installation Manual for details. *1 When four or more control units are connected, connect the power isolator to the NMEA2000 network and provide the external power supply to the backbone. *2 FAP-6112 (optional supply) or third-paty RRUs.

FR-FTPC-CY 10/20/30 m*LAN Cable

Beware of similar products

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